

# GPS: Applications to Distributed Systems and Networks



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- q Principles of operation
- q Current applications
- q Potential applications
- q Obstacles
- q Current products and manufacturers

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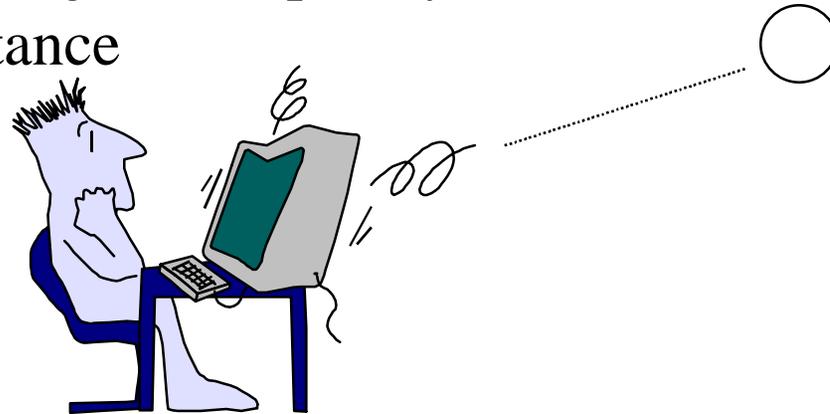
# Executive Summary

- q Precise determination of location, velocity, direction, and time.
- q Price is falling rapidly and applications are growing
- q Goal was to survey current applications
- q Most efforts are in providing navigational guidance to drivers
- q Only two non-navigational applications
- q Identified many new applications of GPS for distributed computing and networking
- q A few obstacles to GPS deployment
- q Detailed lists of GPS products, addresses of manufacturers
- q Sources for further information

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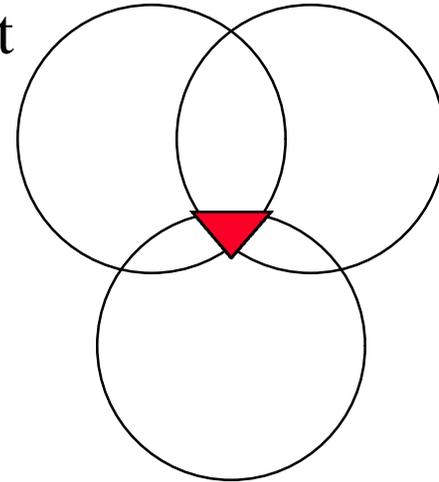
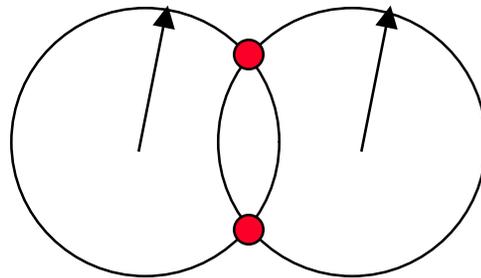
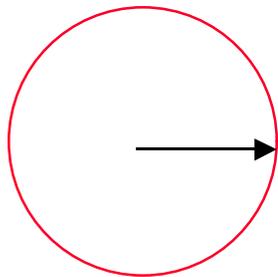
# Introduction

- q Space-based radio positioning system
- q Provide
  - q time
  - q three-dimensional position
  - q velocity
- q First conceived after the launch of Sputnik 1 in 1957
  - q Measuring the frequency shifts in the small beeps  
⇒ Distance



# Principles of Location Determination

- q Broadcast signals allow computing the distance from the satellite
- q Distance from one satellite  $\Rightarrow$  Any point on the circle (sphere)
- q Distance from two satellites  $\Rightarrow$  Two points (circle)  
Ridiculous answer can be eliminated
- q Distance from three satellites  $\Rightarrow$  One point (two points)
- q Distance from four satellites  $\Rightarrow$  One point



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# NAVSTAR

- q Constellation of 24 satellites (Three are spare)
- q Orbiting at a height of 10,900 nautical miles
- q Orbital period of 12 hours
- q Planned life span of 7.5 years
- q Orbits inclined 55 degrees to the equatorial plane
- q Provide a minimum of four satellites in good geometric positions
- q Up to 10 GPS satellites are usually seen
- q Each satellites carries several cesium clocks
- q Positional accuracy of 100 m, Timing accuracy of 300 ns
- q Frequency accuracies of a few parts in  $10^{12}$

# NAVSTAR (Cont)

- q Two L band frequencies, L1 (1575.42 MHz) and L2 (1227.6 MHz)
- q L1 carries a precise (P) code and a coarse/acquisition (C/A) code
- q L2 carries the P code
- q The P code is encrypted (also known as Y code)
- q Only the C/A code is available to civilian users
- q Space vehicle (SV) number: Assigned in order of launch
- q Two services: SPS and PPS

# Standard Positioning Service (SPS)

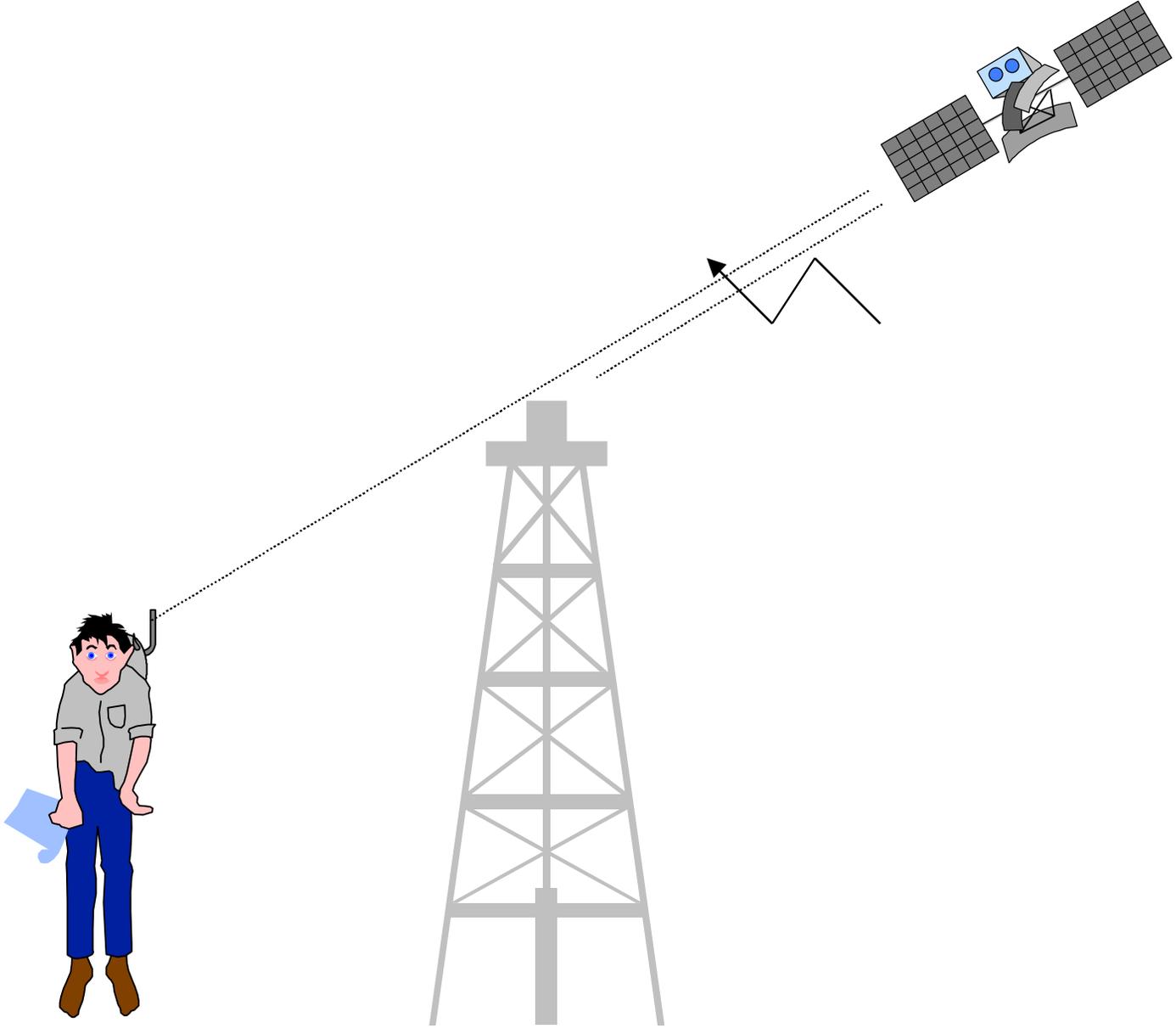
- q Standard level of positioning and timing accuracy
- q Available to any user on a continuous worldwide basis
  - q 100 m horizontal accuracy
  - q 156 meter vertical accuracy
  - q 167 ns time accuracy

# Precise Positioning Service (PPS)

- q Can only be accessed by authorized users with cryptographic equipment and keys
- q US and Allied military and approved civil users
- q Accuracy:
  - q 17.8 meter horizontal
  - q 27.7 m vertical
  - q 100 ns time

# Selective Availability (SA)

- q Intentional degradation by DOD to limit accuracy
- q For non-US military and government users
- q Accuracy of C/A code reduced from 30 m to 100 m



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# Differential GPS (DGPS)

- q Method of eliminating errors in a GPS receiver
- q Assumes most of the errors seen by GPS receivers are common errors
- q Caused by clock deviation, selective availability, drift from predicted orbits, multipath error, internal receiver noise and changing radio propagation conditions in the ionosphere
- q Use a base station with known location to determine error
- q Use the error to correct the location of rovers
- q Continuous broadcast  $\Rightarrow$  real-time DGPS
- q Post-processing correction (Used in surveying)
- q Offers accuracies of few m

# Accurate Time using GPS

- q Time accuracy from GPS signals:
  - q Better than 340 ns (95% probability) using SPS
  - q 100 ns using PPS
- q Inexpensive GPS receivers operating at known positions  
⇒ accuracy of about 0.1  $\mu$ s with only one satellite in view
- q With more sophisticated techniques, one ns is possible (globally)
- q Requires advanced preparation, coordination of the two sites and tracking of specific satellites during specific time periods

# Current Applications of GPS

- q Frequency Counters
- q Intelligent Vehicle Highway Systems (IVHS)
- q Car Navigation Systems
- q Geographic Information Systems (GIS)
- q Emergency Systems: Backpacking
- q Aviation
- q GPS Aides for the Blind
- q Astronomical Telescope Pointing
- q Atmospheric Sounding using GPS Signals
- q Tracking of Wild Animals
- q Recorded Position Information
- q Airborne Gravimetry

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# Commercial Efforts

- q Trimble & Bell Atlantic, Trimble & IBM, PacTel Cellular Wireless & Wireless Solutions Inc:
  - q Vehicle tracking and location devices
- q Ford:
  - q GPS based car alarms to locate stolen cars,
  - q Traffic control, Vehicle tracking, Vehicle recovery, Navigation, Mapping
- q Avis: Testing GPS in rental cars in NYC area
  - q As a navigational aid
- q DeTeMobil:
  - q GPS receivers in all cars in Germany
  - q Pay tolls using smart cards and GSM digital phone

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# Current Distributed Systems and Networking Applications

- q Network delays in DA-30
- q SONET Synchronization

# Network Delays

- q Wandel & Goltermann Inc.
- q DA-30 Internetwork Analyzer uses GPS to make latency measurements between Ethernet LANs linked by a WAN
- q GPS boards lock into the GPS time signal broadcasts
- q S/W conducts latency trials
- q Accurate to within 150  $\mu$ s
- q Requires two kits priced at \$6,750 each

Ref: Government Computer News,  
March 21, 1994, vol. 13, no. 6, p.64.

# SONET Clock Distribution

- q Multiple bit streams to a single network element  
⇒ Need synchronized clocks
- q CCITT Recommendation G.811  
⇒ Long term frequency departure  $\leq 10^{-11}$ .
- q Building Integrated Timing Supply (BITS) is Bellcore's clock-system specification ⇒ Multi-level hierarchy
- q Stratum 1 (ST-1) is the highest quality clock
- q BITS allows LORAN/Rubidium ST1 clock systems
- q AT&T's primary reference clock (PRC) uses GPS signals for long term timing accuracy
- q Rubidium oscillators provide short-term stability

Ref: Telephony, August 24, 1992, pp. 50-54.

# Potential Applications to Distributed Systems and Networks

- q Time applications
- q Position Applications

# Time Applications

- q Circuit Switching Using Synchronized Clocks
- q Synchronous Slotted Systems
- q Clock Synchronization in Distributed System
- q Database Synchronization
- q Connectionless Real-time Communication
- q Real-Time Communications
- q One-Way Delay
- q Delay based routing
- q Time to Live

# Circuit Switching Using Synchronized Clocks

- q Synchronized clocks  $\Rightarrow$  circuit switching easy
- q Precompute switching schedule
- q Similar to synchronized lights on roads

# Synchronous Slotted Systems

- q Slotted systems are less sensitive to distance bandwidth product
- q More suitable for high speed or long distance networks
- q Slotted architectures for all-optical, multi-gigabit networks
- q Need clock synchronization
- q GPS clocks an all-optical ARPA research project

# Clock Synchronization in Distributed System

- q Clock difference  $\leq \Delta$ , Smaller  $\Delta \Rightarrow$  Better system
- q Currently: NTP, OSF-DTS, DECdts, Fuzzbal, timed
- q Future: GPS clocks (1 ns) at least in timeservers
- q Ordering of events (e.g., FCFS scheduling)
- q Consistent update of replicated data
- q At most once receipt of messages
- q Authentication tickets in some systems (e.g., Kerberos)
- q Ensuring atomicity
- q Expiration of privileges
- q Prearranged synchronization
- q Ordering multi-version objects

# Database Synchronization

- q Synchronization after a failure or a disconnected operation
- q Use logs with timestamp to decide the order of actions
- q More precise clocks  $\Rightarrow$  less conflicts

# Connectionless Real-time Communication

- q Delay guarantees on IP-like networks  $\Rightarrow$  Need deadline scheduling
- q GPS  $\Rightarrow$  Deadline timestamp on the packet
- q Similarly, scheduling subtasks of real-time tasks

# One-Way Delay

- q Currently, clock differences  $\geq$  one-way delays  
 $\Rightarrow$  Can't measure one-way delay
- q Round-trip delays used instead
- q Example: ATM networks ABR parameters are  $fn(\text{delay})$
- q GPS synchronized clocks at source and destination  
 $\Rightarrow$  exact one-way delay between source and destination and to every switch can be measured with a single timestamp.

# Delay based routing

- q Internet uses link delays for routing
- q Accurate measurement is difficult
  - ⇒ approximate or round-trip delay used
- q GPS provided exact one-way delay can be used

# Time to Live

- q Helps remove old packets from the networks
- q Currently, the time-to-live field is decremented by 500 ms regardless of actual delay
- q With GPS synchronized clock, exact time-to-live possible

# **Diagnostics/Maintenance of system clocks**

- q A GPS frequency calibrator can be used to periodically check crystals in various equipment

# Time and Frequency Alternatives

- q National Institute of Standards and Technology (NIST)
  - q WWV and WWVH radio broadcasts (accurate to 1 ms)
  - q WWVB broadcasts (2 to 3 parts in  $10^{11}$ )
- q US Naval Observatory (USNO)
  - q Loran-C (LONg RANge Navigation)
  - q Land based radio navigation system
  - q Frequency accuracies of 1 part in  $10^{12}$ , Time better than  $1 \mu\text{s}$
- q Both USNO and NIST provide
  - q Telephone voice messages (accuracy 30 ms)
  - q Computer modem time transfer (several ms)
  - q Remote synchronization of time bases ( $10^{-9}$ ).

# Position Applications

- q Resource Location
- q Location Adaptive Protocols
- q Handoffs in Wireless Networks
- q Prescheduled Hand-overs Based on Velocity and Direction
- q Adaptive Transmission Power Control Algorithm
- q Directional Antennas
- q Temporary Cell Partitioning for Congestion Avoidance
- q Peer-to-peer Routing with Limited Range Receivers
- q Email Delivery Based on Geographic Location
- q Distributed Robot Control and Navigation
- q Equipment Location Marking for Maintenance Crew

# Resource Location

- q Digitized maps and GPS locations
- q Find the nearest printer or fileserver
- q Prescheduling possible

# Location Adaptive Protocols

- q Currently, networking is location transparent
- q Service decisions do not use location
- q In many applications, knowing location helps
- q Examples: Home vs Office vs Car. Electronic Fence.

# Home vs Office vs Car

- q Different physical medium: wire, ISDN, modem, cellular, or radio
- q Different bandwidth bandwidth, cost, and error characteristics
- q Mobile computing decisions =  $\text{fn}(\text{GPS location})$   
Example: Which files to fetch for home vs other town

# Electronic Fence

- q Company confidential papers stay within physical walls
- q GPS provides electronic fence for electronic information
- q Information usable only if computer is within the corporate boundary

# Handoffs in Wireless Networks

- q Inter-cell (change base) or intra-cell (change channel)
- q Decision by base or by mobile unit
- q Currently use signal strength  
Better to use position
- q Avoids passive listening to beacons
- q Simplifies handoff

# Prescheduled Uninterrupted Handoffs

- q Signal strength  $\Rightarrow$  Difficult to predict future
- q GPS location, velocity, and direction  $\Rightarrow$  Future predictable
- q Handoff  $\Rightarrow$  Interruption in service as the packets sent to the previous base have to be forwarded to the new base
- q Prediction  $\Rightarrow$  Prenegotiate the hand-over with all parties

# Adaptive Transmission Power Control Algorithm

- q Battery lifetime is important for mobile computing
- q Little hope for exponential increase in lifetime
- q Need to save battery usage
- q Optimize transmission power
- q Nearby base  $\Rightarrow$  transmit less power
- q Also allow frequency reuse in the same cell

# Directional Antennas

- q Transmission in all directions  $\Rightarrow$  most of the energy wasted
- q GPS  $\Rightarrow$  less power
- q Particularly helpful for satellite communication
- q Also allow better packing density - more users for the same space
- q Provides the minimum radiated RF pattern for covert communications.
- q Can talk to the least busy base unit even if it is not closest unit

# Temporary Cell Partitioning for Congestion Avoidance

- q Cell splitting: Dividing a cell to form new cells
- q Allows reuse of spectrum and helps in reducing congestion
- q Requires prior preparation and usually a permanent change
- q GPS  $\Rightarrow$  dynamic, quick, temporary splitting feasible
- q Can also be used in case of base station failures

# Peer-to-peer Routing with Limited Range Receivers

- q Civilian wireless communication uses base units
- q Military communication  $\Rightarrow$  no pre-existing infrastructure  
 $\Rightarrow$  Better to use peer-to-peer communication
- q Position, heading, velocity, as well as, digital terrain topology information can be used for optimum routing

# Email Delivery Based on Geographic Location

- q Name, addresses, route, and physical position are not related
- q Multicast/anycast to a particular geographic location
- q For example, "to all police cars near Stanford university on route 101"

# Distributed Robot Control and Navigation

- q Intelligent robots can use position and environment information
- q Unmanned vehicles can navigate effectively.

# Equipment Location Marking for Maintenance Crew

- q Service requesters (mobile or stationary) provide GPS location
- q Maintenance crew carry GPS to locate the equipment

# Current Limitations of GPS

- q Selective Availability: degrades achievable accuracies
- q Temporary outage of the receiver as the receiver passes under obstructions  
⇒ GPS for performance not for operation
- q Systems should continue to work without the GPS
- q Like cache memories

# Details of Selected Products

- q Trimble's Mobile GPS Card: Type II PCMCIA GPS sensor by Trimble (\$995). 3 channels tracking up to 8 satellites. 100 m accuracy. Acquisition time of less than 30 s and re-acquisition rate of 2-3 s.
- q Trimble's Mobile GPS Gold Card: Differential-ready (\$1,595). Provides 2-5 m accuracy in real-time.
- q Trimble's Mobile GPS Intelligent Sensor 100: Low-end sensor \$395
- q Rockwell's NavCard PCMCIA GPS sensor
- q Mobile Computing Kit: Includes pen-based TelePad, Proxim's RangeLAN, cellular phone, Trimble GPS, FotoMan Plus camera, ScanMan, AudioMan (\$7,299).

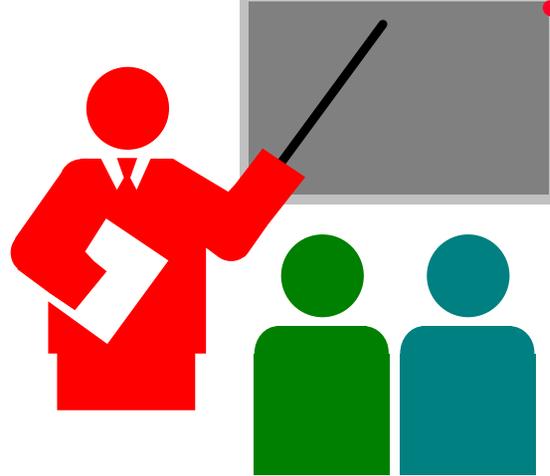
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# GPS Software Applications

- q GPS for windows (\$1,995): By Peacock Systems
- q City Streets for Windows: \$99.95 by Road Scholar software
- q Streets on a Disk: By Kynas Engineering (\$225+\$95/county)
- q Map'n'GO: (\$50) 3CS Software.
- q NCompass 3.0 for Windows: - real time GPS
- q Zagat-Axxis CityGuide: by Axxis Software.
- q MapInfo for Windows 3.0: MapInfo Corp.
- q Atlas GIS for Windows 2.0: By Strategic Mapping Inc.
- q GISPlus for PC: By Caliper Corp.
- q Maptech Professional Marine Chart S/W: (\$1,290) by Resolution Mapping Inc.

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# Summary



- q Cheap PCMCIA receivers for \$300-400  $\Rightarrow$  Growing applications
- q Currently mostly for navigational guidance to drivers
- q SONENT and Wolter and Golderman's DA-30 network analyzer
- q Many many potential applications
- q Main obstacles: Antennas must point to open sky

# References: Books

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- q Ackroyd and Robert Lorimer, *Global Navigation-A GPS users guide*, 2nd Edition, Loyds of London, 1994.

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