

EE464
Transmission Line Equations
(Dally/Poulton Notation)
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Transmission Line Equations

$$V_f(t - \frac{x}{v}) \text{ and } V_r(t + \frac{x}{v})$$

are two traveling waves with V_f propagating in the positive x direction and V_r propagating in the negative x direction. Both move with velocity v .

$$V = V_f + V_r \qquad Z_0 = \sqrt{\frac{L}{C}} \qquad v = \frac{1}{\sqrt{LC}}$$

$$I = I_f + I_r \qquad L = \frac{Z_0}{v} \qquad C = \frac{1}{Z_0 v} \qquad L = \frac{1}{C \cdot v^2}$$

$$V_f = Z_0 I_f \qquad K_{rT} = \frac{Z_T - Z_0}{Z_T + Z_0}$$

$$V_r = -Z_0 I_r \qquad K_{rS} = \frac{Z_S - Z_0}{Z_S + Z_0}$$

Superposition (if linear)

General Equations

$$L \cdot C = 1/v^2 = \mu \cdot \varepsilon$$

$$L/m = 1.112E-17 \cdot \varepsilon_r / (C/m)$$

$$Z_0 = \sqrt{L/C} = 377 / \sqrt{\varepsilon_r} \text{ per square}$$

$$v = \sqrt{1/CL} = (3E10 / \sqrt{\varepsilon_r}) \text{ cm/sec}$$

$$\text{Or } (1 \cdot \sqrt{\varepsilon_r}) \text{ ns/ft} \quad (83 \cdot \sqrt{\varepsilon_r}) \text{ ps/in} \quad (33 \cdot \sqrt{\varepsilon_r}) \text{ ps/cm}$$

Transmission Line Equations

$$V_{fl}(t) = V_{f0}(t - \frac{l}{v})$$

$$V_{r0}(t) = V_{rl}(t + \frac{l}{v})$$

$$V_{f0}(t) = V_S(t) \frac{Z_0}{Z_0 + Z_S} + V_{r0}(t) \frac{Z_S - Z_0}{Z_S + Z_0}$$

$$V_{rl}(t) = V_T(t) \frac{Z_0}{Z_T + Z_0} + V_{fl}(t) \frac{Z_T - Z_0}{Z_T + Z_0}$$

$$V_l = 2V_{fl} \frac{Z_T}{Z_T + Z_0} + V_T \frac{Z_0}{Z_0 + Z_T}$$

$$V_0 = V_S \frac{Z_0}{Z_0 + Z_S} + 2V_{r0} \frac{Z_S}{Z_S + Z_0}$$

General Equations ($V_T = 0$), Use Superposition for Multiple Sources

$$V_{f0}(t) = V_{r0}(t)K_{rS} + V_S(t) \frac{Z_0}{Z_0 + Z_S} \quad 1)$$

$$V_{r0}(t) = V_{f0}\left(t - \frac{2l}{v}\right)K_{rT} \quad 2)$$

2) into 1),

$$V_{f0}(t) = V_{f0}\left(t - \frac{2l}{v}\right)K_{rT} \cdot K_{rS} + V_S(t) \frac{Z_0}{Z_0 + Z_S} \quad 3)$$

At x ,

$$\begin{aligned} V_{fx}(t) &= V_{f0}\left(t - \frac{x}{v}\right) \\ &= V_{f0}\left(t - \frac{2l}{v} - \frac{x}{v}\right)K_{rT} \cdot K_{rS} + V_S\left(t - \frac{x}{v}\right) \frac{Z_0}{Z_0 + Z_S} \end{aligned} \quad 4)$$

From 2) & 3),

$$\begin{aligned} V_{rx}(t) &= V_{f0}\left(t - \frac{4l}{v} + \frac{x}{v}\right)K_{rT}^2 \cdot K_{rS} \\ &\quad + V_S\left(t - \frac{2l}{v} + \frac{x}{v}\right)K_{rT} \cdot \frac{Z_0}{Z_0 + Z_S} \end{aligned} \quad 5)$$

Equations Continued

Repeat 3) into 4), 3) into 5),

$$V_x(t) = \frac{Z_0}{Z_0 + Z_S} \sum_{n=0}^{\infty} \left\{ \underset{\substack{\uparrow \\ V_f}}{V_S(t - \frac{x}{v} - \frac{2nl}{v})} K_{rS}^n \cdot K_{rT}^n + V_S(t - \frac{2(n+1)l}{v} + \frac{x}{v}) \underset{\substack{\uparrow \\ V_r}}{K_{rT}^{n+1}} \cdot \underset{\substack{\uparrow \\ 0^0 = 1}}{K_{rS}^n} \right\}$$

At $x = 0$,

$$V_0(t) = \frac{Z_0}{Z_0 + Z_S} \left[\underset{\substack{\uparrow \\ V_f}}{V_S(t)} + \sum_{n=1}^{\infty} V_S(t - \frac{2nl}{v}) \underset{\substack{\uparrow \\ V_r}}{K_{rT}^n} (\underset{\substack{\uparrow \\ V_r}}{K_{rS}^{n-1}} + \underset{\substack{\uparrow \\ V_f}}{K_{rS}^n}) \right]$$

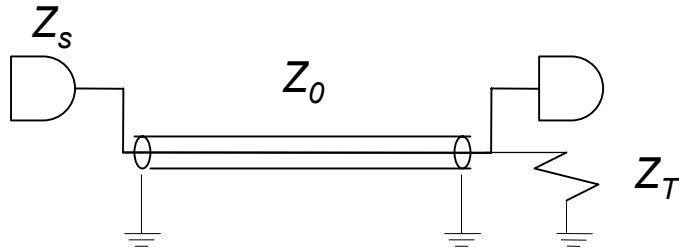
At $x = l$,

$$V_l(t) = \frac{Z_0}{Z_0 + Z_S} \underset{\substack{\uparrow \\ V_f}}{(1 + \underset{\substack{\uparrow \\ V_r}}{K_{rT}})} \sum_{n=0}^{\infty} V_S(t - \frac{2nl}{v} - \frac{l}{v}) \underset{\substack{\uparrow \\ 0^0 = 1}}{K_{rT}^n} \cdot K_{rS}^n$$

Now can find V_0 , V_l at any time.

Example Driving T-Line

Apply to problem,



$$V_S(t) = \begin{cases} 0 & t < 0 \\ 1 & t \geq 0 \end{cases}$$

$$V_l(t) = \frac{Z_0}{Z_0 + Z_S} (1 + K_{rT}) \sum_{n=0}^{\infty} \underbrace{V_S\left(t - \frac{2nl}{v} - \frac{l}{v}\right)}_{}$$

$$= \begin{cases} 1 & t - \frac{(2n+1)l}{v} > 0 \\ 0 & t - \frac{(2n+1)l}{v} < 0 \end{cases}$$

$$= \frac{Z_0}{Z_0 + Z_S} (1 + K_{rT}) \sum_{n=0}^N K_{rT}^n \cdot K_{rS}^n \quad \text{for} \quad \frac{(2N+1)l}{v} < t < \frac{(2N+3)l}{v}$$

Steady State Value and Error Term, Example

With algebra,

$$= \frac{Z_T}{Z_T + Z_S} \left(1 - \underbrace{(K_{rT} \cdot K_{rS})^{N+1}}_{\text{Error} \rightarrow 0 \text{ as } N \rightarrow \infty} \right) \quad \text{for } \frac{(2N+1)l}{v} < t < \frac{(2N+3)l}{v}$$

↑
Attenuation in steady state

For $Z_S = 0$, We get $K_{rS} = -1$

Example: $Z_0 = 100$, $Z_T = 1900$, $Z_S = 0$, $K_{rS} = -1$, $K_{rT} = 0.9$

$$V_l(t) = \frac{Z_T}{Z_T + Z_S} (1 - (-0.9)^{N+1})$$

For error $< 10\%$: $N + 1 = \ln(0.1) / \ln(0.9) = 21.8$, $t = 42.6(l/v)$

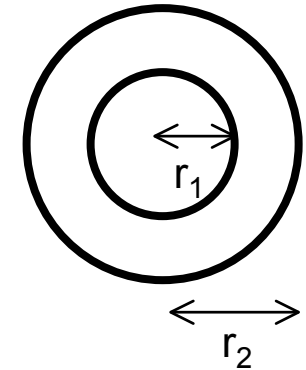
Example Continued

- For 2 foot line, this could be order of 85ns
- What to do?
 - » Wait a long time
 - » Real wire will have some resistance
 - » *CS solution*: use 1900 Ohm transmission Line
 - » Reduce resistance of receiver to match t-line
 - Increased power
 - May be a problem with driver resistance (.e.g 10 to 50 Ohms)
 - » Increase resistance of driver to match t-line
 - 100 Ohms in series with driver gives 2.5% error after only l/v , or after 2ns for one foot line (this is the minimum possible)

Transmission Line Equations for Wire

$$\text{Coax } C = 2\pi\epsilon / \ln(r_2 / r_1) = \epsilon_r \cdot (55.6 \text{ pF} / \text{m}) / \ln(r_2 / r_1)$$

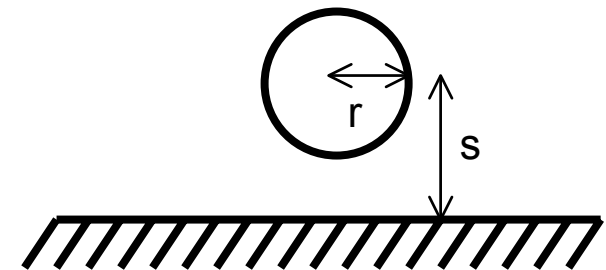
$$Z_0 = (60 / \sqrt{\epsilon_r}) \cdot \ln(r_2 / r_1)$$



Wire over ground plane
(warning, not accurate for r close to s)

$$C / \text{m} = 2 \cdot \pi\epsilon / \ln(2 \cdot s / r) = \epsilon_r \cdot 55.6 (\text{pF} / \text{m}) / \ln(2 \cdot s / r)$$

$$Z_0 = (60 / \sqrt{\epsilon_r}) \cdot \ln(2 \cdot s / r)$$

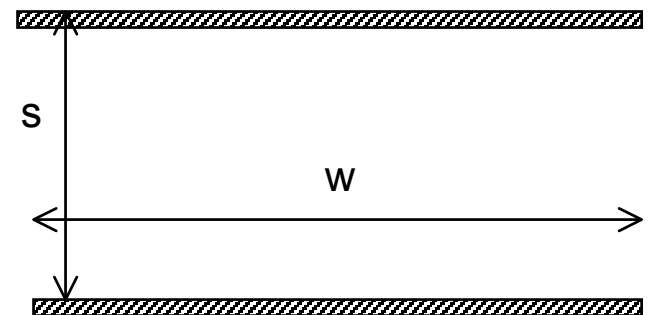


2 Wires: 1/2 capacitance of wire over ground plane

PC Board Equations

$$Z_0 \approx \frac{377}{\sqrt{\epsilon_r}} \frac{s}{w}$$

Parallel Plates
(ignoring fringing)



PC Board Equations

(Careful here, approximations grossly wrong for some values: large w/h)

$$Z_0 \approx \frac{87}{\sqrt{\epsilon_r + 1.41}} \ln\left(\frac{5.98 \cdot h}{0.8 \cdot w + t}\right)$$

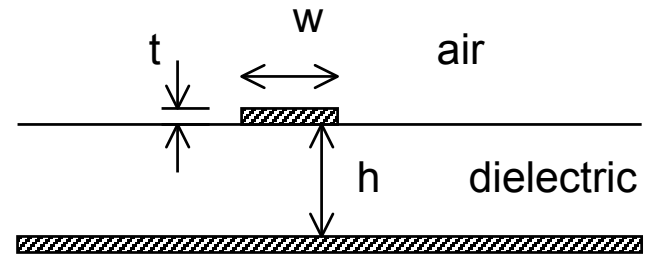
$$t_{pd} (ns / ft) \approx 1.017 \sqrt{0.475 \cdot \epsilon_r + 0.67}$$

$$Z_0 \approx \frac{60}{\sqrt{\epsilon_r}} \ln\left(\frac{4 \cdot b}{0.67 \cdot \pi \cdot w (0.8 + t/w)}\right)$$

for $w/(b-t) < 0.35$, $t/b < 0.25$

$$t_{pd} (ns / ft) \approx 1.017 \sqrt{\epsilon_r}$$

Microstrip



Stripline

